

Chapter 3

THE (CLASSICAL) ACTION PRINCIPLE

3.1 The Action Principle in Mechanics

Consider a system of N degrees of freedom described by a *Lagrangian* $L(q_j, \dot{q}_j)$ as a function of the generalized coordinates

$$q_1(t), q_2(t), \dots, q_N(t)$$

and their velocities. The *Action* functional of the system between time t_i and t_f is defined as

$$\mathcal{S}[\underline{q}; i_i, t_f] \equiv \int_{t_i}^{t_f} dt L(\underline{q}, \dot{\underline{q}}). \quad (3.1)$$

The coordinates $\underline{q}(t)$ describe paths in *Configuration Space*. The actual physical trajectory of the system is one of these paths.

Next, consider functional variations of the coordinates $\delta q_j(t)$ that vanish at the end points, i.e.

$$\delta q_j(t_i) = \delta q_j(t_f) = 0. \quad (3.2)$$

There will be a corresponding variation of the Action $\delta \mathcal{S}$. The *Principle of Least Action* or *Hamilton's Principle* states that the actual physical trajectory of the system corresponds to a *minimum* of the Action

$$\Delta \mathcal{S} = 0. \quad (3.3)$$

This implies¹

$$\begin{aligned} & \int_{t_i}^{t_f} dt \sum_{i=1}^N \left\{ \frac{\partial L}{\partial q_j} \delta q_j + \frac{\partial L}{\partial \dot{q}_j} \delta \dot{q}_j \right\} = \\ & \int_{t_i}^{t_f} dt \sum_{i=1}^N \left\{ \frac{\partial L}{\partial q_j} \delta q_j + \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_j} \delta q_j \right) - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_j} \right) \delta q_j \right\} \\ & = \int_{t_i}^{t_f} dt \sum_j \left\{ \frac{\partial L}{\partial q_j} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_j} \right) \right\} \delta q_j, \end{aligned}$$

or, since the δq 's are arbitrary,

$$\frac{\partial L}{\partial q_j} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_j} \right) = 0. \quad (3.4)$$

These are the *Euler-Lagrange Equations of Motion* of the system.

The *canonical momentum* p_i is defined as $p_i = \frac{\partial L}{\partial \dot{q}_i}$. In terms of it, we may introduce the description of the system in *Phase Space* (q_i, p_i). The *Hamiltonian* is defined as

$$H(q, p) = \sum_i \dot{q}_i p_i - L. \quad (3.5)$$

Starting from the Lagrangean formalism and replacing the velocities with the momenta, the motion of the system can be formulated in terms of H and the *Hamilton Equations of Motion*

$$\dot{q}_i = \frac{\partial H}{\partial p_i}, \quad \dot{p}_i = -\frac{\partial H}{\partial q_i}. \quad (3.6)$$

A free particle of mass m is described by the Action

$$\mathcal{S} = -m \int ds = -m \int dt \sqrt{1 - \left(\frac{d\vec{x}}{dt} \right)^2} \implies L = -m \sqrt{1 - (\dot{\vec{x}})^2}$$

From the canonical momentum of the particle we can arrive at the Hamiltonian

$$\vec{p} = \frac{m\dot{\vec{x}}}{\sqrt{1 - (\dot{\vec{x}})^2}} \implies \dot{\vec{x}} = \frac{\vec{p}}{\sqrt{p^2 + m^2}} \implies H = \dot{\vec{x}} \cdot \vec{p} - L = \sqrt{p^2 + m^2}.$$

¹Note that, since the variations are purely functional, and, therefore, instantaneous, the variation commutes with the time derivative, i.e. $\delta \dot{q} = \frac{d}{dt}(\delta q)$.

3.2 The Action Principle in Field Theory

The above procedure can be generalized and applied to continuous systems described by fields $\phi_a(x^\mu)$, where $x^\mu = (x^0, x^i) = (t, \vec{x})$. The index a stands both for spacetime indices, in case we have vector, spinor or tensor fields, and for internal indices corresponding to multiple fields. Expressing the Lagrangean in terms of a *Lagrange density* $\mathcal{L}(\phi, \partial_\mu\phi)$, we may write the Action in the form

$$\mathcal{S}[\phi] = \int_{t_i}^{t_f} dt L(\phi, \partial_\mu\phi) = \int_{t_i}^{t_f} dt \int d^3x \mathcal{L}(\phi, \partial_\mu\phi) \quad (3.7)$$

or

$$\mathcal{S}[\phi] = \int_{\sigma_i}^{\sigma_f} d^4x \mathcal{L}(\phi, \partial_\mu\phi), \quad (3.8)$$

where $\sigma_{i,f}$ are boundary space-like surfaces.

Introducing variations $\delta\phi_a(x)$ that vanish at the boundary

$$\delta\phi_a(\sigma_i) = \delta\phi_a(\sigma_f) = 0 \quad (3.9)$$

and demanding a minimum of the Action $\delta\mathcal{S} = 0$ for the physical system trajectory, we obtain

$$\begin{aligned} \int d^4x \sum_a \left\{ \frac{\partial\mathcal{L}}{\partial\phi_a} \delta\phi_a + \partial_\mu \left(\frac{\partial\mathcal{L}}{\partial\partial_\mu\phi_a} \delta\phi_a \right) - \partial_\mu \left(\frac{\partial\mathcal{L}}{\partial\partial_\mu\phi_a} \right) \delta\phi_a \right\} \\ = \int d^4x \sum_a \left\{ \frac{\partial\mathcal{L}}{\partial\phi_a} - \partial_\mu \left(\frac{\partial\mathcal{L}}{\partial\partial_\mu\phi_a} \right) \right\} \delta\phi_a = 0 \end{aligned}$$

or

$$\frac{\partial\mathcal{L}}{\partial\phi_a} - \partial_\mu \left(\frac{\partial\mathcal{L}}{\partial\partial_\mu\phi_a} \right) = 0. \quad (3.10)$$

These are the *Euler-Lagrange Equations of Motion* for the fields ϕ_a .

The canonical formalism² can be set up as in the case of systems with finite degrees of freedom. The *canonical momenta* corresponding to the fields ϕ_a are defined as

$$\pi_a(x) \equiv \frac{\partial\mathcal{L}}{\partial\dot{\phi}_a}. \quad (3.11)$$

²The description of a system in terms of fields and momenta is referred to as *canonical formalism*.

The *Hamiltonian* of the system is

$$H \equiv \int d^3x \mathcal{H}(\phi, \pi) \quad (3.12)$$

in terms of the *Hamiltonian density*, defined as

$$\mathcal{H}(\phi_a, \pi_a) \equiv \dot{\phi}_a \pi_a - \mathcal{L}. \quad (3.13)$$

The evolution of the system of fields in the canonical formalism is described by *Hamilton's Equations*

$$\dot{\phi}_a = \frac{\partial \mathcal{H}}{\partial \pi_a}, \quad \dot{\pi}_a = -\frac{\partial \mathcal{H}}{\partial \phi_a}. \quad (3.14)$$

An example of a relativistic continuous system is supplied by a real scalar field. The simplest Lagrange density that describes a free scalar field is

$$\mathcal{L} = \frac{1}{2}(\partial_\mu \phi)(\partial^\mu \phi) - \frac{m^2}{2}\phi^2 \quad (3.15)$$

and leads to the *Klein-Gordon equation*

$$\left(\square + m^2\right)\phi(x) = 0. \quad (3.16)$$

The general solution of the Klein-Gordon equation can be expanded in plane waves $e^{-ik \cdot x}$ as

$$\phi(x) = \int \frac{d^3k}{(2\pi)^{3/2}\sqrt{2\omega}} \left(a(k) e^{-ik \cdot x} + a^*(k) e^{ik \cdot x} \right), \quad (3.17)$$

where $\omega(k) = k^0 = \sqrt{\vec{k}^2 + m^2}$.

The canonical momentum corresponding to $\phi(x)$ is $\pi(x) = \dot{\phi}(x)$. The Hamiltonian is

$$H = \int d^3x \frac{1}{2} \left(\pi^2 + (\vec{\nabla}\phi)^2 + m^2\phi^2 \right). \quad (3.18)$$